

Lecture 16

• Indef of Path

A v.f. is independent of path if the line integral

$$\int_C \vec{F} \cdot d\vec{r}$$

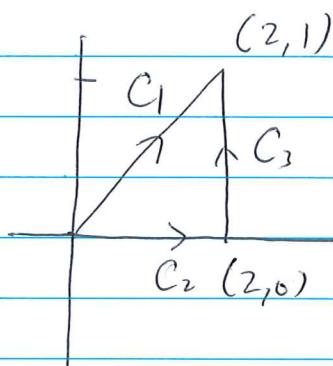
produces the same value from any curve C from points A to B. This is very special.

e.g.

$$C_1 \quad \gamma_1(t) = (2t, t), \quad t \in [0, 1]$$

$$C_2 \quad \gamma_2(t) = (2t, 0), \quad t \in [0, 1]$$

$$C_3 \quad \gamma_3(t) = (2, t), \quad t \in [0, 1]$$



$\vec{F}(x, y) = (y, x^2)$. We've

$$\int_{C_1} \vec{F} \cdot d\vec{r} = \int_0^1 (t, 4t^2) \cdot (2, 1) dt = 1 + \frac{4}{3} = \frac{7}{3}.$$

$$\int_{C_2} \vec{F} \cdot d\vec{r} = \int_0^1 (0, 4t^2) \cdot (2, 0) dt = 0.$$

$$\int_{C_3} \vec{F} \cdot d\vec{r} = \int_0^1 (t, 4) \cdot (0, 1) dt = 4.$$

After both C_1 and $C_2 + C_3$ go from $A(0,0)$ to $B(2,1)$, but

$$\int_{C_1} \vec{F} \cdot d\vec{r} \neq \int_{C_2 + C_3} \vec{F} \cdot d\vec{r}.$$

It turns out the property of independence of path characterizes gradient vector fields.

Theorem 1 \vec{F} is a gradient v.f. $\Rightarrow \vec{F}$ is independent of path.

Some terminologies =

gradient v.f. = conservative v.f. = conservative force

path = piecewise regular curve

PF : Let Φ be a potential for \vec{F} . Take $n=2$ ($n \geq 3$ similar)

$$\vec{F} = (P, Q), \nabla \Phi = \vec{F} \Leftrightarrow$$

$$\frac{\partial \Phi}{\partial x} = P, \frac{\partial \Phi}{\partial y} = Q.$$

Let A, B be 2 pts and C_1, C_2 two paths from A to B,

Need to show

$$\int_{C_1} \vec{F} \cdot d\vec{r} = \int_{C_2} \vec{F} \cdot d\vec{r}.$$

Let $C = C_i, i=1,2$. and first assume C is regular.

$$\int_C \vec{F} \cdot d\vec{r} = \int_a^b P(\gamma(t)) x'(t) + Q(\gamma(t)) y'(t) dt$$

where $\gamma: [a, b] \rightarrow C$ is a parametrization of C. Then

$$= \int_a^b P(x(t), y(t)) x'(t) + Q(x(t), y(t)) y'(t) dt$$

$$= \int_a^b \frac{\partial \Phi}{\partial x}(x(t), y(t)) x'(t) + \frac{\partial \Phi}{\partial y}(x(t), y(t)) y'(t) dt$$

$$= \int_a^b \frac{d}{dt} \Phi(x(t), y(t)) dt \quad (\text{Thanks to Chain Rule})$$

$$= \Phi(x(t), y(t)) \Big|_a^b$$

$$= \Phi(y(b)) - \Phi(y(a))$$

$$= \Phi(B) - \Phi(A)$$

Hence no matter it is C_1 or C_2 ,

$$\int_{C_i} \vec{F} \cdot d\vec{r} = \Phi(B) - \Phi(A), \quad i=1, 2, \quad (1)$$

and the R.H.S. only depends on the values of Φ at the endpt.,

When C is piecewise regular, let's assume, say
Remark (Useful formula).

$C = C_1 + C_2$ where C_1 sums from A to E , C_2 sums from E to B ; are regular (that is, only E is a non-diff. pt).

Applying (1) to C_1, C_2 to get

$$\int_C \vec{F} \cdot d\vec{r} = \int_{C_1 + C_2} \vec{F} \cdot d\vec{r} = \int_{C_1} \vec{F} \cdot d\vec{r} + \int_{C_2} \vec{F} \cdot d\vec{r}$$

$$= \Phi(E) - \Phi(A) + \Phi(B) - \Phi(E)$$

$$= \Phi(B) - \Phi(A),$$

(1) still holds. When there are several non-diff. pts, it is clear that (1) is still valid. $\#$

Remark (1) is a useful formula.

Now we prove the converse.

Theorem \vec{F} is idft of path $\Rightarrow \vec{F}$ is a gradient v.f.

Proof. Fix a pt A inside the region. For any $B(x, y)$ inside,

define

$$\Phi(x, y) = \int_C \vec{F} \cdot d\vec{r}$$

where C is any path from A to $B(x, y)$. It is well-defined because \vec{F} is idft of path.

Now, let C_h be the path $t \mapsto (x+th, y)$, $t \in [0, 1]$ where h is a small number. Then $C + C_h$ is a path from A to the pt $(x+h, y)$. So

$$\begin{aligned} \Phi(x+h, y) - \Phi(x, y) &= \int_{C+C_h} \vec{F} \cdot d\vec{r} - \int_C \vec{F} \cdot d\vec{r} \\ &= \int_C \vec{F} \cdot d\vec{r} + \int_{C_h} \vec{F} \cdot d\vec{r} - \int_C \vec{F} \cdot d\vec{r} \end{aligned}$$

$$\gamma(t) = (x+th, y)$$

$$\gamma'(t) = (h, 0)$$

$$= \int_{C_h} \vec{F} \cdot d\vec{r}$$

$$= \int_0^1 [P(x+th, y)h + Q(x+th, y)0] dt$$

$$= P \int_0^1 P(x+th, y) dt.$$

$$\therefore \frac{\Phi(x+h, y) - \Phi(x, y)}{h} = \int_0^1 P(x+th, y) dt$$

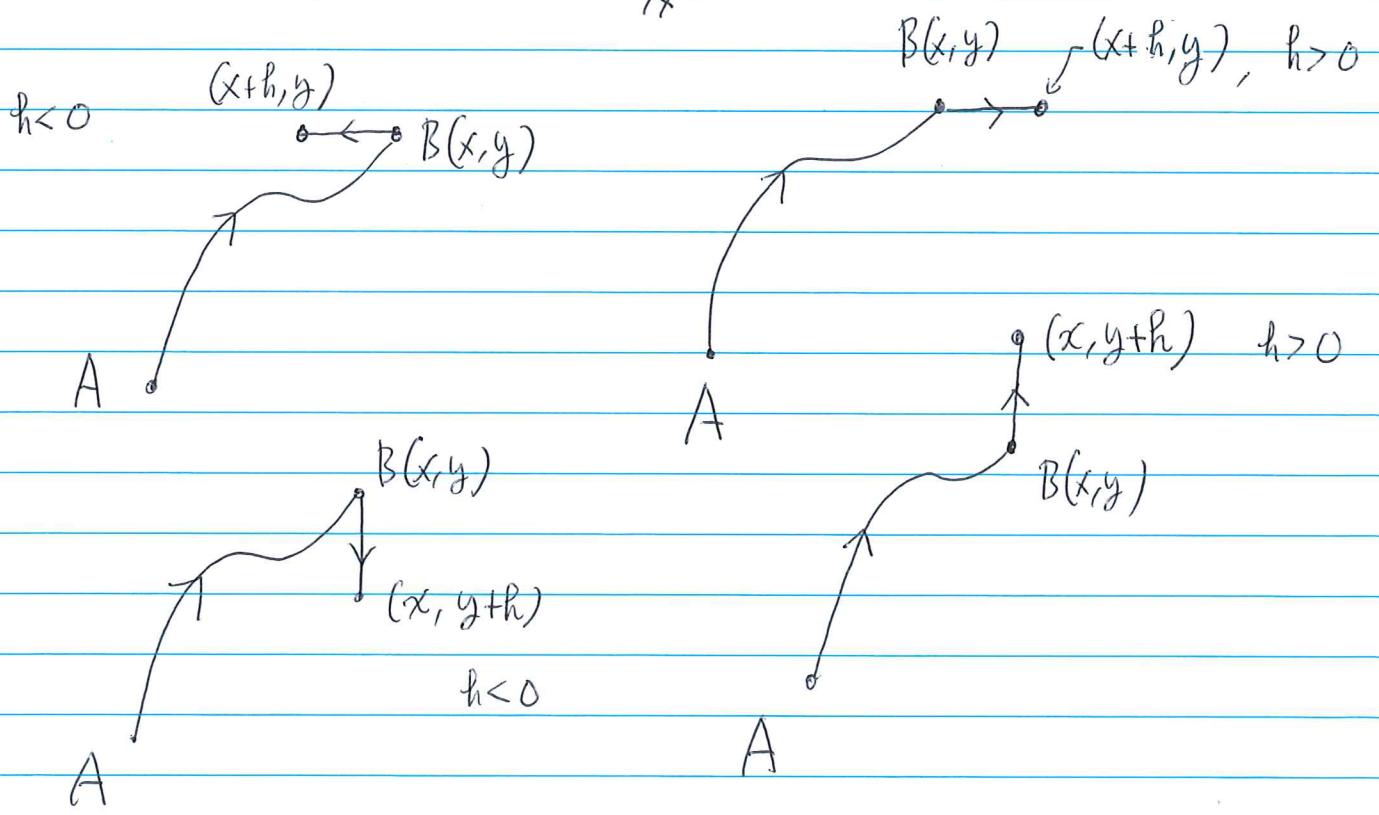
$$\therefore \frac{\partial \Phi}{\partial x}(x, y) = \lim_{h \rightarrow 0} \frac{\Phi(x+h, y) - \Phi(x, y)}{h}$$

$$= \lim_{h \rightarrow 0} \int_0^1 P(x+th, y) dt$$

$$= P(x, y).$$

Similarly, we can show that $\frac{\partial \Phi}{\partial y}$ exists and equals to $Q(x, y)$.

$M/3$ are similarly treated. ~~✓~~



There is an equivalent formulation for indep of path. Let's denote by

$$\oint_C \vec{F} \cdot d\vec{r}$$

when C is a closed loop, that is, a curve without endpts.

Theorem A v.f. \vec{F} is indep of path if and only if

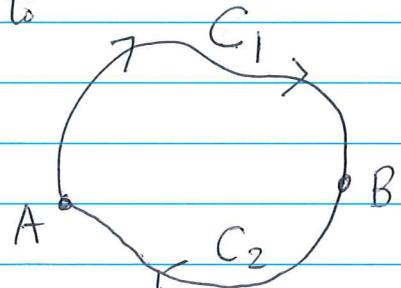
$$\oint_C \vec{F} \cdot d\vec{r} = 0$$

for every closed loop C .

Pf : \Rightarrow Pick ² pts A, B on C and denote C_1 the curve from A to B and C_2 the curve from B to A so that $C = C_1 + C_2$. Now, $-C_2$ is a curve from A to B .

By assumption,

$$\int_{C_1} \vec{F} \cdot d\vec{r} = \int_{-C_2} \vec{F} \cdot d\vec{r}.$$



Using $\int_{-C_2} \vec{F} \cdot d\vec{r} = -\int_{C_2} \vec{F} \cdot d\vec{r}$, we get

$$\oint_C \vec{F} \cdot d\vec{r} = \int_{C_1} \vec{F} \cdot d\vec{r} + \int_{C_2} \vec{F} \cdot d\vec{r} = -\int_{C_2} \vec{F} \cdot d\vec{r} + \int_{C_2} \vec{F} \cdot d\vec{r} = 0.$$

\Leftarrow) Let C_1, C_2 two paths from A to B . Then $C = C_1 - C_2$ is a closed loop. So

$$0 = \oint_C \vec{F} \cdot d\vec{r} = \int_{C_1} \vec{F} \cdot d\vec{r} + \int_{-C_2} \vec{F} \cdot d\vec{r}$$

L7

$$= \int_{C_1} \vec{F} \cdot d\vec{r} - \int_{C_2} \vec{F} \cdot d\vec{r}, \text{ ie}$$

$$\int_{C_1} \vec{F} \cdot d\vec{r} = \int_{C_2} \vec{F} \cdot d\vec{r}. \quad \#$$